


# Arrhythmia Detection Using Deep Belief Network Extracted Features From ECG Signals


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## ABSTRACT

Arrhythmia is a disorder of the heart caused by the erratic nature of heartbeats occurring due to conduction failures of the electrical signals in the cardiac muscle. In recent years, research has been done towards accurate categorization of heartbeats and electrocardiogram (ECG)-based heartbeat processing. Accurate categorization of different heartbeats is an important step for diagnosis of arrhythmia. This paper primarily focuses on effective feature extraction of the ECG signals for model performance enhancement using an unsupervised deep belief network (DBN) pipelined onto a simple logistic regression (LR) classifier. The authors compare and evaluate the results of data feature enrichment against plain, non-enriched data based on the metrics of precision, recall, specificity, and F1-score and report the extent of increase in performance. Also, they compare the performance of the DBN-LR pipeline with a 1D convolution technique and find that the DBN-LR algorithm achieves a 5% and 10% increase in accuracy when compared to 1D convolution and no feature extraction using DBN, respectively.

## KEYWORDS

Boltzmann Machines, Deep Belief Networks, Deep Neural Networks, ECG-Based Heartbeat Detection, Feature Extraction, Logistic Regression, Machine Learning

## 1. INTRODUCTION

Heart arrhythmia is a category of heart disease which results from any disturbances in the rate, uniformity, and site origin or conduction of the cardiac electric impulse (Thaler, 1999). By examining and analyzing the combination of action impulse waveforms of the electrical signal of each heartbeat which are produced by various specialized cardiac tissues present in the heart, detection

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**Table 1. Categorization of heartbeats using AAMI EC57 (Association for the Advancement of Medical Instrumentation, 1998) categories and annotations**

Annotations	Category
Normal beats / Left or Right bundle branch block	N
Supraventricular ectopic beats / Aberrant atrial premature / Supra-ventricular premature / Nodal premature	S
Ventricular ectopic beats / Ventricular Escape	V
Fusion beats (of ventricular and normal)	F
Unknown or Unclassifiable beats (Paced or fusion of paced and normal)	Q

of abnormalities is possible (Luz et al., 2016). For the diagnosis of cardiac arrhythmia or any other heart rhythm disorder, electrocardiogram (ECG) is one of the most frequently used methods which helps in measuring and monitoring the impulses of the heart in the form of waveforms as it is non-invasive and efficient as well as an accurate method that provides useful information related to the heart impulse and other required details.

The muscles of the human heart contract and relax rhythmically for blood circulation throughout the body. Atrial sine node being the site of initial contractions act as a natural pacemaker and further pass through the other muscles. These electric signals propagate in a specific manner and follow a pattern (Herone and Smith, 2003), generating light electrical currents on the surface of the skin. These electrical signals are then measured with the help of electrodes and other appropriate devices. Electrodes measure the electric potential difference between the points and are amplified with optic isolation using suitable devices. Then these generated signals are passed through a high pass, followed by a low pass filter. At last, these signals are finally converted from analog signals to digital signals. This process of generating a graphical representation of digital signals done by the electrocardiogram (ECG) (Luz et al., 2016).

Recently, heart diseases have emerged as a major problem due to high rates of incidence and mortality. The treatment cost is another factor making it a serious disease as it requires long-term treatment and frequently entails expensive therapies for cure (Mozzafarian et al., 2015; National Center for Health Statistics, 2005). Every year, 17.34 million deaths are recorded owing to diseases that are related to the heart which in total accounts for 37% of the total deaths globally (Smith et al., 2005; Healthsquare, 2007; World Health Organization, 2014). Due to these reasons, with an expected progressive aging of the population globally, it may lead to an increased number of deaths from 17 million in 2016 to 24 million by 2030 (de Chazal et al., 2004). Many heart-related diseases can be diagnosed early via machine learning techniques (Anand et al., 2020; Das et al., 2020) and frequent itemset mining (Nayak et al., 2019). Several cases of arrhythmia appear as sequences of heartbeats with different timing or variation of ECG morphology. Classification of the correct type of heartbeat is an important step for the diagnosis of arrhythmia. The electric rhythm generated from the ECG signal is determined by analyzing and determining the consecutive heartbeats in the signal (Elhaj et al., 2016). According to the Association for the Advancement of Medical Instrumentation (AAMI), a heartbeat is further classified into five different categories which help in the diagnosis of arrhythmia (Association for the Advancement of Medical Instrumentation, 1998; Spach and Kootsey, 1983). Table 1 shows the categories of irregular heartbeats with their respective annotations.

According to the American Heart Association (AMA), over 70 million people around the world had been diagnosed with cardiovascular diseases (Elhaj et al., 2016). Data on the country-wise spread of arrhythmia or atrial fibrillation remains largely unorganized and inaccessible in general media. This may be due to poor surveillance across various developing and even developing countries.

Moreover, (Sidney et al., 2013) the amassment of the data provided by the Heart Disease and Stroke Statistics Update does not comprise timely and representative data on stroke incidence and heart diseases in the USA.

The problem statement that we tackle through this paper is to correctly classify the category of arrhythmia (N, S, V, F, or Q) given the digitized ambulatory ECG recordings of a mixed cohort of patients recorded at 360 samples per second per channel (Mark and Moody, 1998). Techniques such as 1D convolution (Li, D. et al., 2017) require complex preprocessing of the signals before the data is deemed suitable for the 1D convolution. This necessitates the use of prominent single-step feature extraction practices working over low-level preprocessed data so that the model formation complexity is reduced with little-to-no compromises made on detection metrics.

Related technology mainly used for the detection of the category of arrhythmia include 1D convolution, adaptive filtering before detection (Thakor and Zhu, 1991), use of non-linear dynamical modeling (Owis et al., 2002), supervised neural networks (Hannun et al., 2019), autocorrelation function (Guillén et al., 1990), via time-frequency analysis (Afonoso and Tompkins, 1995), using wavelet transform (Khadra et al., 1997), etc. Adaptive filtering makes use of various structures of filters to get rid of noise, these structures are baseline wander, 60 Hz power line interference, motion effect, and muscle noise. In this context, adaptive recurrent filter structures may be used (Thakor and Zhu, 1991) to analyze ECG signals and to categorize them. Another traditional method to model arrhythmia detection is by using non-linear dynamical modeling (Owis et al., 2002) where five categories of ECG are classified using the largest Lyapunov exponent and correlation dimension. Apart from the traditional approaches, because of recent developments made in machine and deep learning, supervised neural networks have been employed for the detection of arrhythmia as done in (Hannun et al., 2019). However, in this paper, we employ the unsupervised counterparts of traditional artificial neural networks that belong to the Boltzmann machine family (GM et al., 2021a). We use a generative model (GM et al., 2020) to generate high level features extracted from the ECG signals that resemble the original data distribution.

All the samples that are obtained from the MIT-BIH database have a constant frequency of 125Hz. Process of arrhythmia identification and classification can be difficult for humans to detect because at times it becomes a mandatory job to monitor each heartbeat from the ECG records which might require sitting of hours and hours or even days and hence, there are high chances of encountering a human error during the process of analyzing due to ambiguity in the signal forms. Today, machine learning techniques have eased the burden of pattern recognition from humans in almost every sector of the industry. From finance such as in credit card fraud detection (Sahu et al., 2020) to web analytics in sentiment analysis (Chandra et al., 2021), machine learning has made a profound impact. However, even for machine learning models, such ambiguities make performance inconsistent over classifying the types of new a patient's signals. To avoid this, in this paper, we present a powerful feature extraction tool using a Bayesian network namely Deep Belief Network (DBN) which falls in the part of unsupervised deep learning. Classifier applied on the feature extracted vector done by the DBNs shows superior performance as opposed to no feature extraction and helps in automatic decision making and categorizing the type of arrhythmia disease very accurately. Our contributions in this paper are as follows:

1. We use an unconventional method of unsupervised deep learning namely deep belief network to extract useful ECG features.
2. A logistic regression classifier is used to work upon the DBN features to form an end-to-end pipeline for the categorization of arrhythmias.
3. Various metrics such as precision, recall, specificity, and F1-score are used for comparison of results.
4. We implement another approach that makes use of 1D convolution for comparison with the DBN approach.

5. We present a comparison of the results of work with other studies done in the past.

The main novelty of our work lies in the fact that, to the best of our knowledge, no study has used DBN in the past and done a comprehensive analysis of the results by i) comparison with an unconventional technique such as 1D convolution, ii) with more than three performance metrics, and iii) by providing a comparison as to how no extraction of features using DBN affects performance (as we shall see in Section 4).

The rest of the paper is organized as follows: 2. *Related work*, 3. *Methodology and Data*, 4. *Experimentation and results*, 5. *Future Directions* and 6. *Conclusion*. An analytical and comprehensive evaluation of the applied algorithm has been done and also been compared with other work done in the literature.

## 2. RELATED WORK

Many researchers are in the process of creating new algorithms and techniques for the development and advancement of medical diagnostic tools. Lately, different techniques using neural networks have been implemented for the diagnosis as well treatment of various diseases with overwhelming results. Different researches have mainly focused on feature extraction and selection of a small dataset of non-redundant, predictive features for ECG graphical representation. Authors in (Ince et al., 2009; Jiang and Kong, 2007; Martis et al., 2013; Ye et al., 2012) have implemented different types of feature extraction like Hermite transform, discrete wavelet transform, and independent component analysis. Different types of feature extraction were combined and used sequentially to optimize the set of discriminant features for the classification of arrhythmia type (Chen et al., 2017; Mar et al., 2011; Teijeiro et al., 2018). Authors in (Mar et al., 2011) employed used an algorithm named as sequential forward floating search to select prominent features over which a multilayer perceptron is trained. In (Chen et al., 2017), an ECG beat classification is performed based on a mixture of dynamic and projected features. Various classifiers based on the ECG features have been implemented in the study which includes hidden Markov models (Pan et al., 2012), MOE (mixture of experts) approach (Hu et al., 1997), SVM (support vector machine) (Chen et al., 2017), BBNN (blocked-based neural network) (Jiang and Kong, 2017), regression neural networks (Li, P. et al., 2017), genetic algorithm-back propagation neural network (Li, H. et al., 2017), and artificial neural networks (Jadhav et al., 2010; Sannino and Pietro, 2018).

In recent studies, it is found that convolutional neural networks (CNNs)-based models with feature enrichment show accurate and efficient results in analyzing not only ECG signals but also EEG (Electroencephalogram) signals (Acharya et al., 2017b, 2018). LeCun et al. (1990) implemented CNN back in 1990 which today is considered to be one of the flagship neural networks. Rapid development in GPU (Graphics Process Unit) technology helps CNN in outperforming with much higher accuracy and efficiency with much lesser loss in image recognition (Krizhevsky et al., 2012), audio classification (Hinton et al., 2012), and many more. CNN shows promising applications in time series bio-signals like ECG (Acharya et al., 2017a; Al Rahhal et al., 2016; Kiranyaz and Gabbouj, 2016; Yildirim et al., 2018).

In the study proposed by Hu et al. (1997), work is done on customization of different heartbeat classifiers of specific patients and then combined with the classifiers that were developed from the ECG signal database. The MOE approach was used in the study to combine the classifiers. The paper reported 62.2% of accuracy while 94% accuracy with MOE classifier when categorizing ventricular ectopic beats from non-ventricular ectopic beats. Another study by Lagerholm et al. (2000) mentioned a method involving the formation of clusters or groups of 25 ECG records which gave an experimental accuracy of 98.5% of the correctness of the prediction of the group of the heartbeat signals. Rajpurkar et al. (2017) worked on the classification of atrial fibrillation and implemented it on 30000 patients' ECG signals.

Different approaches of CNN are used in classifying the ECG signals. For instance, Inan et al. (2006) used dyadic wavelet transform and neural networks to achieve 95.16% accuracy. Sayadi et al. (2010) used the Kalman and Bayesian filters to get an accuracy of 99.10%, with 98.77% of sensitivity and 97.4% in specificity. Martis et al. (2011) implemented higher-order statistics, wavelet packet decomposition, and SVM (support vector machine) classifier to obtain accuracy, sensitivity, and specificity as 98.40%, 98.90%, and 98% respectively, whereas, Prasad et al. (2013) used three approaches: higher-order statistics, independent component analysis, and KNN (K-nearest neighbors) classifier for the model and reported results as 97.65% of accuracy, 98.75% of sensitivity, and 99.53% of specificity. Li et al. (2016) used wavelet packet decomposition and RR intervals with wavelet packet entropy and random forest classifier to predict the targets with an accuracy of 94.61%. Another study proposed by Acharya et al. (2017b) implemented a nine-layer CNN, who divided the whole dataset into two parts: with noise and without noise and worked in the generation of synthetic data and achieved the results in accuracy, sensitivity, and specificity of set 1: 93.47%, 96.01%, and 91.64% respectively and for set 2: 94.03%, 96.71%, and 91.54%.

In this paper, we use feature enrichment using DBNs of the preprocessed (the preprocessing details are given later in Section 3.2) ECG signals before training a logistic classifier model to improve the overall accuracy and minimize the losses. We also compare this approach to a 1D convolutional neural network performing ECG detections on the same dataset.

### 3. METHODOLOGY AND DATA

This section contains the methods used in our feature extraction-based ECG signal classification model. We also specify the preprocessing of raw ECG data to transform data into a suitable form for the DBN. The section is further divided into subsections: 3.1 *Dataset used and Model Workflow*, 3.2 *Data Preprocessing*, 3.3 *Restricted Boltzmann Machines (RBMs)*, 3.4 *Deep Belief Networks (DBNs)*, 3.5 *Logistic Regression Classifier*. We study RBMs ahead of DBNs because RBMs are used as a pre-training step for DBNs.

#### 3.1 Dataset Used and Model Workflow

All the ECG signals are collected from MIT-BIH Arrhythmia dataset (Mark and Moody, 1998). This dataset is available publicly which has been widely used for performance evaluation of different ECG-based heartbeat classification algorithms. The dataset contains a total of 109446 records of patients. All records are classified into five categories as shown in Table 2.

A full automatic model for the detection process of arrhythmia disease classification with the help of ECG generated signals mainly requires four steps which are shown in Figure 1 and are:

1. ECG signal preprocessing, generating from the heartbeat signal of the patient.
2. Splitting of preprocessed signals into training and test set (8:2 split) and further into the training and testing sets of labels and data.
3. Normalization of training and testing data for better model performance.
4. Applying DBN for feature extraction on training data and labels.
5. Applying logistic regression classifier on enriched feature vector (output of DBN block) and testing for performance metrics on test data and labels.

Figure 2 shows a line graph of each class based on the data provided.

We further describe the types of heartbeats classified by N, S, V, F, and Q.

Figure 1. Model workflow for feature enriched classification of ECG signals

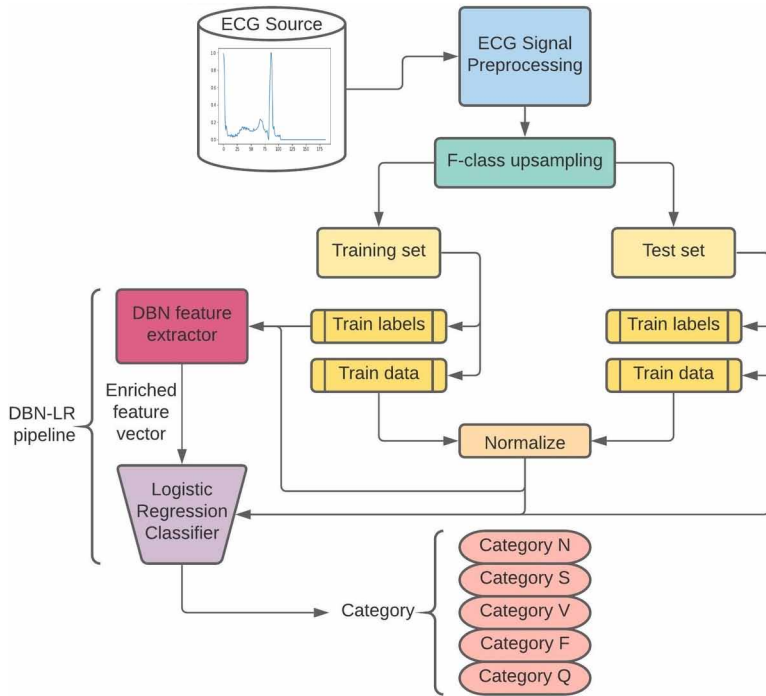


Table 2. Original composition of the number of class records

Category	Number of records
N	72471
S	2223
V	5788
F	641
Q	6431

Figure 2. Line graphs (a), (b), (c), (d) and (e) for classes N, S, V, F, Q respectively

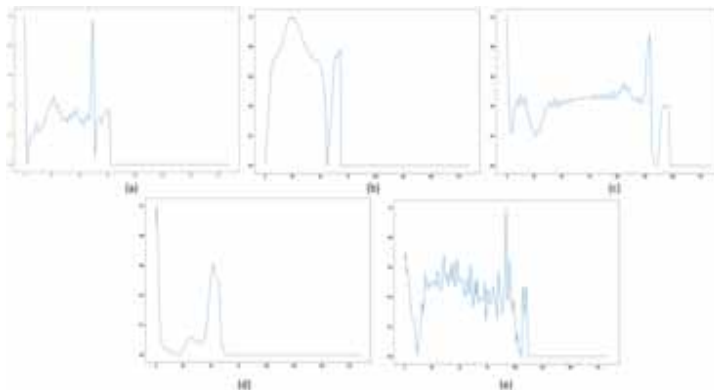
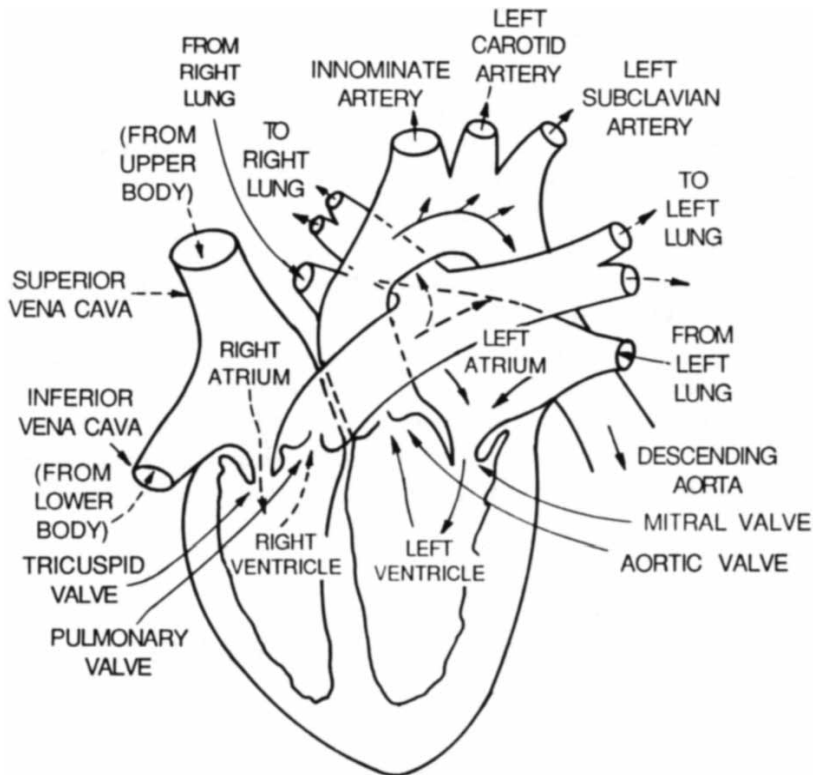


Figure 3. Ottesen et al. (2004). The four-chambered heart.



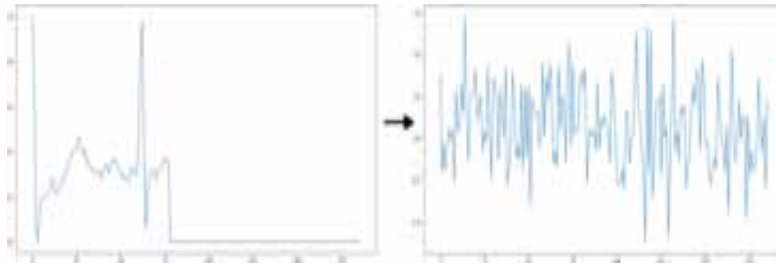
### 3.1.1 N Categorization

The N category beats are usually classified as normal heartbeats or left / right bundle branch block. The heart is composed of 4 chambers (the upper two are the right and left atria while the lower two are called ventricles) as shown in Figure 3. The electrical signal of the initialization of a heartbeat starts at the right atrium which travels to the left atrium and from there down to the ventricles. There are two bundle branches responsible for the conduction of the electrical signal to the ventricular section so those may beat. These bundles are termed the left and the right bundle. However, there may be a problem with the left or right branch of the conduction system which is termed as the left or right bundle branch block accordingly. In this problem, the signals do not normally travel downwards and are delayed due to the spread of the conduction signal from the right bundle branch via the cardiac muscle to gradually activate the left ventricle. When the left ventricle has a delayed contraction, there is a lack of coordination in the contraction of the cardiac muscles. This problem may be visible from the N categorization of the ECG signals.

### 3.1.2 S Categorization

Ectopic beats generally mean erratic heartbeat rhythms which may occur due to an earlier beat. Ectopic rhythm is also known as premature atrial contraction, extrasystole, and premature ventricular contraction. Usually, when this occurs, there is an early beat followed by a bolder beat of the heart. This occurs generally with normal, healthy people occasionally. Premature atrial contraction refers to the early beat originating from the right or left atria. This condition is very common among healthy children and is virtually harmless. Likewise, when the early beat arises from the ventricular region

Figure 4. Addition of Gaussian noise with input ECG signals. The input signal (left) transforms to a new signal with added Gaussian noise (right).



of the heart, is known as premature ventricular contraction. The risk of having premature ventricular contractions increases with age.

### 3.1.3 V Categorization

Ventricular escape occurs when the electrical conduction system fails due to a heart block of all the bundles. This generates an impulse from a ventricular focus. These may even occur after long pauses in ventricular rhythm and is an impulsive action to avoid cardiac arrest. When the conduction system fails, there is an absence of heartbeats since the heart is unable to simulate the ventricles, which is when the ventricular escape is noticed.

### 3.1.4 F Categorization

The F class represents the fusion of ventricular ectopic and normal heartbeats.

### 3.1.5 Q Categorization

The heartbeats which are not classifiable according to the above conventions are placed into this category. The fusion of paced and normal beats along with only paced are also categorized into the Q class.

## 3.2 Data Pre-Processing

Usually, deep learning algorithms require large datasets to be trained upon for smooth functioning. We notice from Table 2 that there is a scenario of data imbalance. Class F only contains 641 instances as compared to class N with an overwhelming 72471 number of instances. We solve this by augmenting or resampling the data of class F and increasing it to 2000 instances in which new instances are made through random duplication. Likewise, 2000 instances of each class are taken to move forward with a balanced dataset.

Secondly, we apply a random Gaussian noise represented by the probability density function

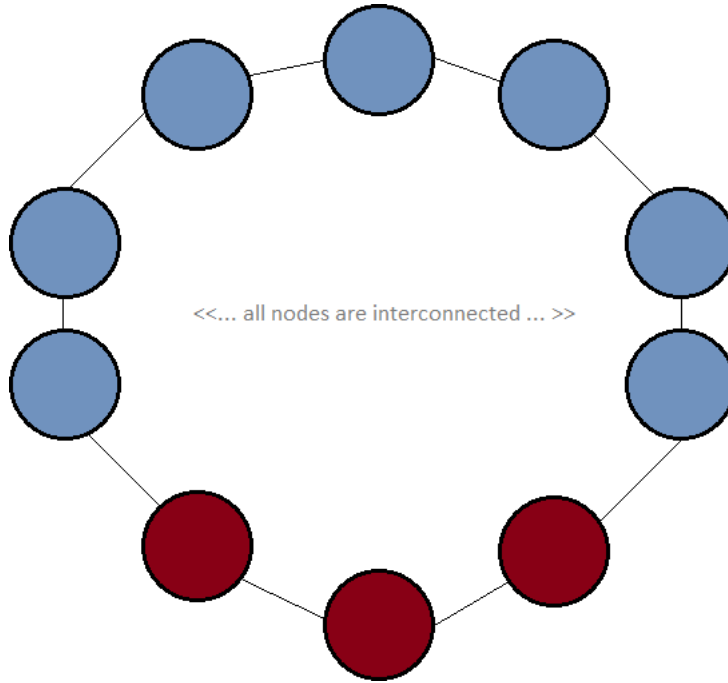
$P_g(z)$  given by:

$$P_g(z) = \frac{1}{\sigma\sqrt{2\pi}} \exp\left(-\frac{(z-\mu)^2}{2\sigma^2}\right) \quad (1)$$

In eqn. (1),  $z$  denotes the grey level, with  $\mu$  and  $\sigma$  being the mean and standard deviation. We draw random samples from a Gaussian distribution centered at the origin and a standard deviation of 0.05 and add to the input signals to increase the variability of the data for generalization and better model performance. Figure 4 shows the effects of Gaussian noise on the input signal.



Figure 5. Typical Boltzmann Machine where maroon circles represent theoretically visible nodes and blue ones represent hidden nodes



Thirdly, we normalize the test and train data as depicted by Figure 1 as:

$$f_{norm}(x_i) = \frac{x_i - \min(x)}{\max(x) - \min(x)} \quad (2)$$

Normalization of values is necessary for setting a common scale so that the machine learning algorithms can efficiently learn.

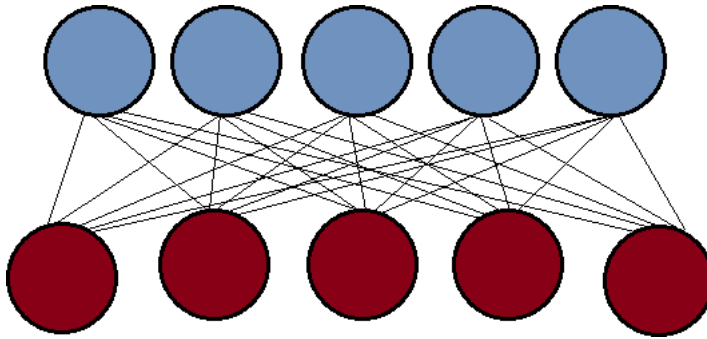
### 3.3 Restricted Boltzmann Machines (RBMs)

Restricted Boltzmann Machines are a derivative of the parent Boltzmann Machine (BM) model shown by Figure 5.

BMs comprise many interlinked nodes having weighted connections. BMs represent the unsupervised categorization of deep learning models which generate different states of a given input system to model it. They are one of the prominent generative models in machine learning which create data that closely resembles the given input. After the input is provided to the input nodes, through a method named *contrastive divergence*, involving a process named Gibbs' sampling which is a technique of the Monte Carlo family, the hidden nodes feed the visible nodes in an iterative manner, and also the visible nodes feed the hidden ones, being multiplied by the weighted connections between them. The problem with this architecture was the large overhead on CPUs due to the many connections involving all the nodes being connected to all the other nodes. The RBM solves this problem.

To solve this, RBMs do away with the connections between the same types of nodes. In other words, no connections are made between visible and hidden nodes, and vice-versa. Doing so results

Figure 6. Restricted Boltzmann Machine



in a structure illustrated by Figure 6. BMs and RBMs generally are energy-based models (LeCun, 2006) which define a joint configuration  $E(v, h)$  (Hopfield, 1982) which can be illustrated as:

$$E(v, h) = - \sum_{i \in \text{visible}} p_i v_i - \sum_{j \in \text{hidden}} q_j h_j - \sum_i \sum_j w_{i,j} v_i h_j \quad (3)$$

The terms  $h_j$  and  $v_i$  refer to the hidden node  $j$  and visible node  $i$  respectively. Between these nodes, the weights and biases are given by  $w_{i,j}$ , and  $q_j$  and  $p_i$  respectively. The probability  $p(v, h)$  is assigned as follows:

$$p(v, h) = \frac{\exp(-E(v, h))}{\sum_{v, h} \exp(-E(v, h))} \quad (4)$$

Through contrastive divergence, a gradient for learning is acquired as given by eqn. (5) using which the RBM determines the lowest energy state (which is also the most probable state of the system) through adjustment of weights:

$$\frac{\delta \log p(v^{initial})}{\delta w_{i,j}} = \langle v_i^{initial} h_j^{initial} \rangle - \langle v_i^{final} h_j^{final} \rangle \quad (5)$$

### 3.4 Deep Belief Networks (DBNs)

DBNs may be thought of as RBMs stacked on top of each other. DBNs have a complex training procedure to eliminate problems such as the independence of the prior situated at the last hidden layer and another phenomenon called *explaining away*. *Explaining away* is a phenomenon observed in Bayesian networks where inference of hidden variables in hidden layers is intractable because their posterior over hidden variables is also intractable. In simpler terms, explaining away is observed when, one of the causes provides an explanation of the effect. This results in the reduction of the probability of occurrence of other causes. Let us take a logistic belief network that has randomly initialized binary units (Neal, 1992) to help generate data. All of unit  $i$  is probabilities of activations

are a sigmoidal function of the unit's prior neighbours  $j$  and the weights among them  $w_{i,j}$  (where the connections are as  $i \rightarrow j$ ). For all neighbours of unit  $i$ , given by the prior  $j$ , there is a sigmoidal function. If  $w_{i,j}$  denotes the weights amongst these units, then:

$$P(s_i = 1) = \frac{1}{1 + \exp(-b_i - \sum_j s_j w_{i,j})} \quad (6)$$

In eqn. (6),  $b_i$  is the bias of  $i^{\text{th}}$  unit. In our experiments, we consider there to be only one hidden layer which can be termed as *factorial*. This means that all the hidden units that have conditional independence. However, due to the likelihood term propagating through from the input vector, the same is not true for the posterior. In (Hinton et al., 2006), authors proposed that the problematic *explaining away* can be eliminated with the existence of a complimentary prior that has an opposite correlation to the likelihood term. A factorial posterior is obtained because of the product of prior and likelihood term.

Data generation in an infinite belief network is shown in Figure 7 which is similar to RBM's method of generation. The hidden nodes are connected to visible nodes and vice-versa. The RBM is can be seen as a reduction of the traditional BM to be sized down to a two-layer ( $v, h$ ) RBM having numerous contrastive divergence walks. This is known as the pre-training of the RBM before training of DBN. Authors in (Hinton et al., 2006) proposed a greedy learning algorithm for DBN that learns layer-wise as we describe below.

As described above, initially an RBM is trained to learn the data  $x$ . Let  $R(c^1 | c^0)$  be the posterior over  $c^1$  where  $c^0$  is the input data vector  $x$ . Now, we obtain an empirical distribution  $\hat{d}^1$  over the layer  $c^1$  when sampling  $c^0$  from  $\hat{d}$  (Bengio et al., 2007):

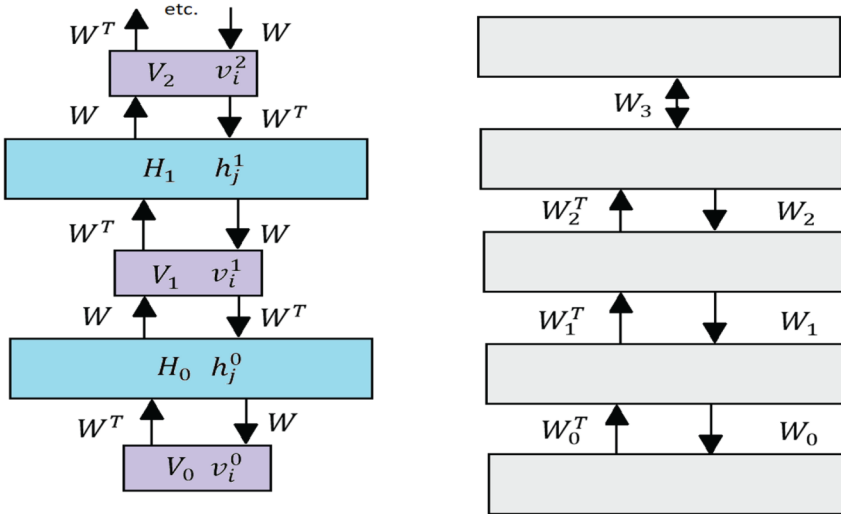
$$\hat{d}^1(c^1) = \sum_{c^0} \hat{d}(c^0) R(c^1 | c^0) \quad (7)$$

Now, once the RBM is trained, it is placed atop the DBN at position  $(n + 1)$ . Thus,  $R(c^{n-1} | c^n)$  corresponds to  $D(c^{n-1} | c^n)$  where  $D(\cdot)$  represents the distribution of the posterior of the DBN. Thus, we can say that  $R(c^{n-1} | c^n)$  is approximately equivalent to the posterior  $D(c^{n-1} | c^n)$ . Now we can eliminate the *explaining away* effect as the deepest hidden layer now has an independent prior. Thus, the elimination of *explaining away* is possible because of the independence of the prior at the last hidden layer. Using eqn. (7), it is possible to show:

$$\hat{d}^n(c^n) = \sum_{c^{n-1}} \hat{d}^{n-1}(c^{n-1}) R(c^n | c^{n-1}) \quad (8)$$

Using eqn. (8) the samples  $c^{n-1}$  with distribution  $\hat{d}^{n-1}$  are stochastically transformed to  $c^n$  with distribution  $\hat{d}^n$ . Sampling from  $c^n$  in an unbiased manner is now possible which is then fed downward stochastically by  $R(c^i | c^{i-1})$ . Now we have an approximate posterior of  $x$  clamped at  $c^0$  by the lower hidden units. We can approximate posteriors  $D(c^i | c^0)$  through mean-field approximation (as proposed in (Hinton et al., 2006)) by transformation of samples  $c_j^{i-1}$  from level  $i - 1$  where

Figure 7. The weights in the infinite logistic belief net are tied. When data flows from down to up, the sampling of inference from posterior distribution takes place and this is not related to generative modelling of the DBN. In the opposite sense, the generative model can be represented by the downward arrows. (Right): The bidirectional connections between two deep-most layers represent an RBM and the connections flowing from top to down are the generative model. The bottom to up connections infer a factorial representation from the layer beneath each layer. The bottom-up and top-down weights are initially tied in greedy learning.



$j \in \{0, 1, \dots, m^i - 1\}$  as  $m^i$  represents the total number of units in the  $i^{\text{th}}$  layer. Transformation of each sample via mean-field expected value  $E_j^{i-1}$  can be done where:

$$E^i = \sigma(b_j^i + W^i E^{i-1}) \quad (9)$$

where:

$$\sigma(x) = \frac{1}{1 + e^{-x}} \quad (10)$$

Eqn. (10) is called the sigmoid function used in logistic models (as we shall also see in Section. 3.5). Eqn. (10) is most commonly termed as the logistic or the sigmoid function. The weight matrix pertaining to the  $i^{\text{th}}$  layer is given by  $W^i$ , while the bias of the unit  $j$  situated at the  $i^{\text{th}}$  layer is given by  $b_j^i$ . Authors in (Hinton et al., 2006) put forward the generic DBN equations as follows:

$$D(c^i | c^{i+1}) = \prod_{j=1}^{m^i} D(c_j^i | c^{i+1}) \quad (11)$$

$$D(c_j^i = 1 | c^{i+1}) = \sigma\left(b_j^i + \sum_{k=1}^{m^{i+1}} W_{kj}^i c_k^{i+1}\right) \quad (12)$$

Table 3. DBN configuration settings

Hidden Layer Structure	Batch Size	Learning Rate (RBM)	# Epochs	Activation Function
{256, 512}	10	0.06	10	Sigmoid

### 3.5 Logistic Regression Classifier

The logistic regression classifier is a simple machine learning model which learns the relationships or the patterns represented between binary variables. Given a vector of  $n$  independent variables by set  $X = \{x_1, x_2, \dots, x_n\}$ , the target variable  $Y$  (or, dependent variable) is calculated through eqn. (13) where  $p = P(Y = 1)$ :

$$\log_e \left( \frac{p}{1-p} \right) = \beta_0 + \beta_1 x_1 + \beta_2 x_2 + \dots + \beta_n x_n \quad (13)$$

Solving eqn. (13) further, we can obtain the logistic sigmoid function as seen earlier in eqn. (10):

$$p = \frac{1}{1 + e^{-(\beta_0 + \beta_1 x_1 + \beta_2 x_2 + \dots + \beta_n x_n)}} \quad (14)$$

## 4. EXPERIMENTATION AND RESULTS

In this section, we present the results of training a logistic regression classifier on a feature vector selected by training the DBN on the ECG MIT-BIH dataset. All experiments performed were done using Anaconda Python 3.5 on a CPU having 8 GB RAM with Intel Core i5 8<sup>th</sup> generation 1.8 GHz processor on Windows 10 with NVIDIA MX130 GPU. We specify the configuration settings for training the DBN in Table 3. The hidden layer structure {256, 512} refers to having 256 hidden nodes in the first hidden layer and 512 hidden nodes in the second hidden layer. The RBM reconstruction errors encountered in each epoch are given in Figure 8. We train the algorithm for only 10 epochs since it is clear from Figure 8 that the model converges at epoch 8 and the error is constant henceforth. Further training may have resulted in overfitting.

To compare our approach, we use another approach using 1D convolutional neural networks. Convolutional neural networks have been used for the detection of ECG by various researchers (Huang et al., 2019; Jun et al., 2018; Sharma et al., 2020). The configuration of this network is given in Table 4. The total number of parameters for the model was 118,341 with 117,957 trainable and 384 non-trainable parameters. As for training history, the model accuracy and loss have been plotted in Figure 9 and Figure 10 respectively.

To obtain a comparative result, we train the same dataset on the raw preprocessed data and feed it into the logistic classifier without selection of features by DBN and illustrate how much the results vary. Table 8 shows the performance difference of the three approaches based on five metrics *accuracy, precision, recall, specificity, and F1-score*. These metrics are defined as:

$$\text{Accuracy} = \frac{(TP + TN)}{(TP + FP + FN + TN)} \quad (15)$$

Figure 8. RBM reconstruction error encountered during pre-training the DBN

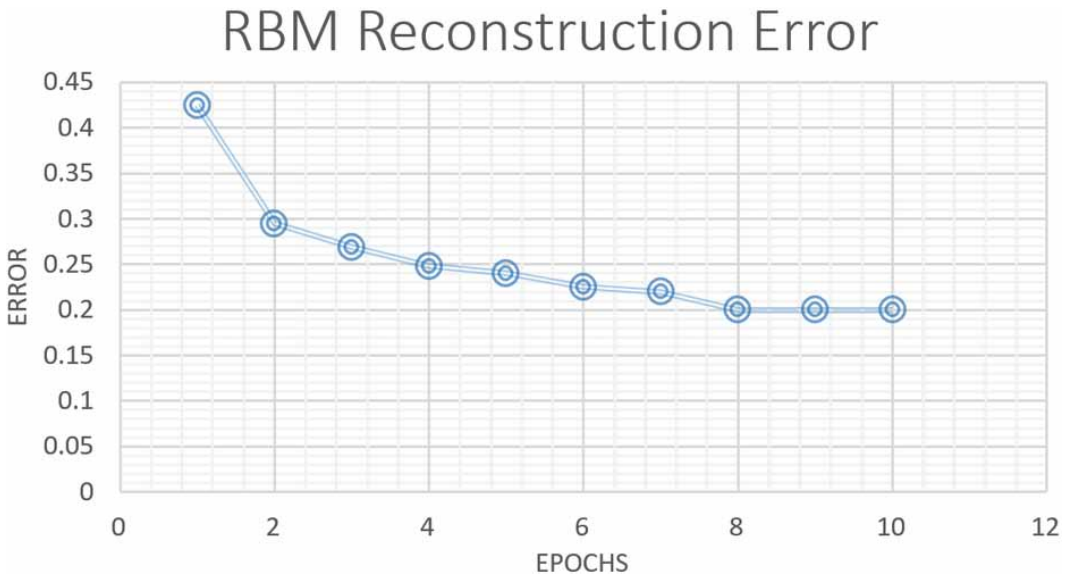
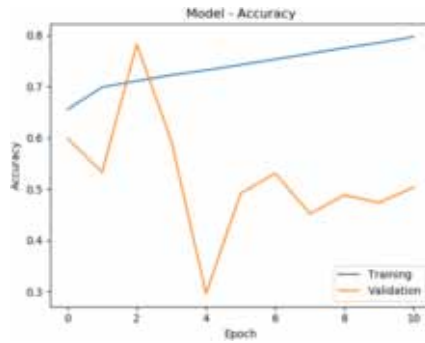


Table 4. 1D convolutional neural network configuration. The algorithm was trained using TensorFlow's Keras on Python 3.

Layer (no. of filters)	Size	Activation	Output shape	Parameters
Conv1D (64)	6 × 6	ReLU	(None, 181, 64)	448
BatchNorm	-	-	(None, 181, 64)	256
MaxPooling1D	3 × 3	-	(None, 91, 64)	0
Conv1D (64)	3 × 3	ReLU	(None, 89, 64)	12352
BatchNorm	-	-	(None, 89, 64)	256
MaxPooling1D	2 × 2	-	(None, 45, 64)	0
Conv1D (64)	3 × 3	ReLU	(None, 43, 64)	12352
BatchNorm	-	-	(None, 43, 64)	256
MaxPooling1D	2 × 2	-	(None, 22, 64)	0
Flatten	-	-	(None, 1408)	0
Dense	64	ReLU	(None, 64)	90176
Dense	32	ReLU	(None, 32)	2080
Dense_output	5	Softmax	(None, 5)	165

Figure 9. 1D convolution training history in terms of accuracy



$$\text{Precision} = \frac{TP}{(TP + FP)} \quad (16)$$

$$\text{Recall} = \frac{TP}{(TP + FN)} \quad (17)$$

$$\text{Specificity} = \frac{TN}{(TN + FP)} \quad (18)$$

Figure 10. 1D convolution training history in terms of loss

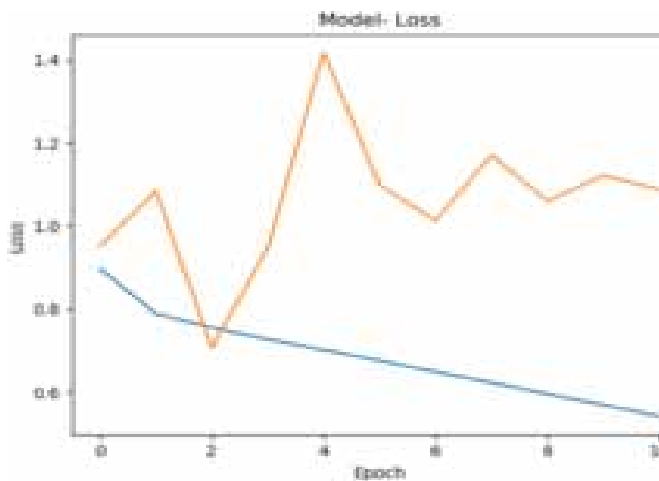


Table 5. Confusion matrix of DBN with extracted features

	N	S	V	F	Q
N	14066	67	7	17	11
S	256	361	2	3	6
V	65	8	1137	11	5
F	63	3	8	364	1
Q	42	4	2	4	1262

$$F1 = 2 \left( \frac{\text{Precision} \times \text{Recall}}{\text{Precision} + \text{Recall}} \right) = \frac{2TP}{2TP + FP + FN} \quad (19)$$

In eqns. (15), (16), (17), (18), and (19), *TP*, *TN*, *FP*, and *FN* refer to *true positive*, *true negative*, *false positive*, and *false negative* respectively. We further define the terms precision, recall, specificity, and F1 score in terms of a binary classification problem. Precision is defined as the ratio of the positive observations that the model correctly predicted to the total number of predicted positive observations. Whereas, recall, also referred to as *sensitivity*, is the ratio of the positive observations that the model correctly predicted to all the observations in the actual class of ‘positive’. Specificity can be thought of as the probability that the prediction is negative given that the true observation is also negative. F1 score is just the weighted average of precision and recall. One important thing to note about using the F1 score on multi-class classification problems is that a higher F1 score does not always necessarily mean that it is a better classifier.

More specifically, the F1 score takes the weighted average of precision and recall. This means that it gives equal weight to both precision and recall. However, in classification problems (even binary), this is hardly the case. The importance of precision and recall varies from problem to problem. As an example, misclassifying a healthy person as a sick person does not have the same implication as misclassifying a sick person as healthy. In the same way, this importance of classification and misclassification of pairs of classes increases due to the increase in the number of possible pairs of classes in multi-class problems. Hence, F1 scores do not take into consideration if, say in our application, misclassifying N as S is more dangerous than misclassifying S as N. Table 5, Table 6, and Table 6 are the confusion matrices generated by the DBN-LR model, LR model, and the 1D convolution model respectively. We calculate all our metrics from these results.

P, R, S, and F1 refer to precision, recall, specificity, and F1 score respectively in Table 8. It can be clearly seen that feature extraction using DBN leads to superior results as compared to normal classification approaches without feature extraction. The classifier is better able to identify the classes

Table 6. Confusion matrix with no extraction of features

	N	S	V	F	Q
N	12613	113	74	36	92
S	1052	301	14	15	37
V	360	19	1001	39	42
F	281	4	63	296	23
Q	187	6	5	13	1090



Table 7. Confusion matrix for 1D convolution approach

	N	S	V	F	Q
N	<b>17985</b>	26	26	39	42
S	375	<b>156</b>	24	0	1
V	736	20	<b>545</b>	4	143
F	112	0	1	<b>48</b>	1
Q	237	0	0	0	<b>1371</b>

of the ECG signals given a more specific set of data rather than the whole data of the signals. Our DBN is successfully able to do this by extracting important hidden features from the signals and feeding them into the logistic classifier. We compute the macro average for the metrics precision and recall achieved by our DBN-Logistic model to be 0.91 and 0.928 respectively. From Table 8 it is evident that the DBN-LR pipeline augments the detection accuracy by 10% and also outperforms the 1D convolution detection accuracy on various metrics including accuracy.

The bold values in Table 8 should be interpreted class-wise (i.e. row-wise). These values indicate the highest value in the row, and as a result of multiple highest values, all such instances have been made bold in the same row. It can be seen that although 1D convolution also compares with our approach in terms of precision on class N, specificity on class S, and specificity on class F. However, most of the highest values reside in the DBN extracted features block and this is also supported by the highest accuracy of 96.7% achieved by our approach.

These results are promising as DBN can be used as an efficient feature extractor. These features can then be fed into prominent classifiers (in this study, we have only used logistic regression). Further, we compare our results with some of the results attained by other works in the literature as listed in Table 9. It is important to note that the final accuracy achieved is not the main aspect to be inspected, however, it is, in fact, the increase in the accuracy. This is because researchers may use DBN as a feature extractor instead of a logistic regression classifier as we have done. Convolutional neural networks are the gold standard when it comes to image classification, but we argue that DBN can also be considered as a competent algorithm for feature extraction in certain use-cases. Pipelines such as DBN-ANN (where ANN stands for artificial neural network), DBN-RF (random forest), and

Table 8. Comparison of feature extraction using DBN vs. no feature extraction vs. 1D convolution based on defined performance metrics

Class	DBN extracted features				No feature extraction				1D Convolution			
	P	R	S	F1	P	R	S	F1	P	R	S	F1
N	<b>0.99</b>	0.97	0.96	0.98	0.98	0.87	0.90	0.92	<b>0.99</b>	0.92	0.94	0.96
S	0.57	0.81	<b>0.98</b>	0.67	0.21	0.68	0.93	0.32	0.28	0.77	<b>0.98</b>	0.41
V	0.93	0.98	<b>0.99</b>	0.95	0.70	0.87	0.97	0.78	0.38	0.91	0.95	0.53
F	0.83	0.91	<b>0.99</b>	0.87	0.44	0.81	0.97	0.57	0.30	0.53	<b>0.99</b>	0.38
Q	0.96	0.98	<b>0.99</b>	0.97	0.84	0.85	0.98	0.84	0.85	0.88	0.98	0.87
Acc.	<b>0.967</b>				<b>0.863</b>				<b>0.91</b>			

DBN-XGBoost could result in even better final accuracy. Moreover, the performance augment given

**Table 9. Comparison of our results with related work. Avg. in the column header indicates the average of all values obtained for different classes or types for the given metric**

Related Work	Precision (avg.)	Recall (avg.)	Specificity (avg.)	F1-score (avg.)	Accuracy
Acharya et al. (2017b)	0.97	0.96	0.91	N/A	0.94
Sayadi et al. (2010)	0.74	0.75	N/A	N/A	0.99
Prasad et al. (2013)	0.98	0.98	0.98	N/A	0.98
Martis et al. (2011)	0.98	0.98	0.98	N/A	0.97
Li et al. (2016)	0.93	0.94	-	N/A	0.94
<b>Our work</b>	<b>0.91</b>	<b>0.92</b>	<b>0.98</b>	<b>0.88</b>	<b>0.967</b>

by DBN is not promised for every application – this means that DBN may not help with increasing accuracy when, say, it is applied for detection of breast cancer. More along these lines is provided in Section 5.1.

The metrics we achieve in this paper, in comparison to existing studies, may not be superior to them. However, as mentioned earlier, the important aspect of this research work is to examine whether DBN improves detection accuracy for a generic classifier when used as a feature extractor.

## 5. FUTURE DIRECTIONS

For future work the occurrence, sequential patterns, and persistence of five categories of ECG signals’ heartbeats: N, S, V, F, and Q can be grouped in three prominent categories: Red, Yellow, and Green which represent danger, abnormal, and normal conditions of heart activity depending upon the electrical signals generated by ECG. We also insinuate the use of new techniques for capturing ECG signals (*Ex: off-the-person approach*), for the development of new datasets. The creation of such new datasets will be a challenging task not only because of the financial cost involved but also the dataset has to be incorporated into standards such as AAMI to reach the desired audience.

While working on this study we noticed that there are very few novel studies on feature extraction of ECG signals using Bayesian deep neural networks. These features are usually extracted in the time domain itself (Mazomenos et al., 2012) or its frequency domain transforms (Lin, 2008). More examples of such feature extractions are by the use of Karhunen-Loeve Transform, Hermitian Basis, Discrete Wavelet Transform, Short-Term Fourier Transform, etc. One possible future direction to take could be the transformation of ECG signals into one of the aforementioned transforms and then applying deep neural networks to extract features for even better performance of the predictive models. Further, we discuss certain strengths and limitations of our work. Moreover, as discussed earlier, researchers can use DBN as a preliminary feature extractor and apply different algorithms to create pipelines such as DBN-ANN, DBN-RF, DBN-XGBoost, etc. for better results.

### 5.1 Strengths and Limitations

In this study, we explored how DBNs can be used as a tool for amassing higher-order features for input to a classifier to improve performance metrics, as seen in Table 8. The main advantage of using DBN in this application is that we saw that the performance increase in terms of accuracy can be as high as 10%. This augment in performance ability for any classifier has profound applications for other areas of medical research where the classification of diseases is crucial for patient prognoses (Jee et al., 2021; Yıldırım et al., 2018). This accuracy increase is also noticed when compared to 1D convolution. Moreover, the DBN, being a generative model, can generate its own samples based on the features it learned while training. If we sample the different representations from the DBN, we

can understand what the model considered as important. This makes the model intelligible – in other words, it helps explain why the predictions were made the way they were. Intelligibility is critical in machine learning models when used for clinical applications, and hence, to understand the predictions, less powerful approaches with lesser accuracy may be chosen over more powerful, higher accuracy-yielding approaches (like neural networks) which act essentially like a black-box. Hence, DBN acts as both, a powerful feature extractor and also as an intelligible model.

There are some limitations to this study. Hyperparameter tuning could have been done to find optimum parameters for the DBN, however, this would result in a long model forming process. Also, the methodology used here does not beat all performance metrics attained by other studies as seen in Table 9. This is because the DBN is a generative model and is better at generating data rather than having it being used as a discriminator. In this study, the DBN is used as a feature extractor – and the way it does this is by generating features when given an input vector of ECG signals. The generated features for some classes, at times, maybe imprecise owing to the complexity of a quintuple classification problem. Training DBNs is also very computationally expensive as these run on Markov chains. Lastly, there do not exist any well-defined frameworks for the implementation of DBNs – researchers are mostly left searching for viable solutions and code to their specific tasks and often are required to write their implementation from scratch. Hence, the flexibility of implementation of DBNs (finding more suitable versions of DBN implementations rather than those found on-line) is still an active area of application of unsupervised deep learning techniques.

## 6. CONCLUSION

In the proposed study, a deep learning approach is implemented for making an automatic categorizing heartbeat model with different ECG heartbeat signals which is an important step for the diagnosis of arrhythmia disease. DBN feature extraction pipelined with logistic regression classifier is used in the model. We compare this approach to (a) no feature extraction for logistic regression classifier, and (b) 1D convolutional neural network. The study shows that feature enrichment plays an important role in accurately classifying the data, as with feature extraction the accuracy improved from 86% to 96%. Similar results were observed as the DBN-Logistic model gave superior results to 1D convolution (5% increase in accuracy). The experiments were performed on the MIT-BIH dataset and the proposed method is found to be efficient and accurate based on the performance metrics of precision, recall, specificity, F1 score and accuracy. Based on the results achieved by the model, the same methods can be implemented into computer-aided design (CAD) ECG systems for getting quick, efficient, and reliable performance for diagnosis. Our model can be implemented in polyclinics to online and offline screen a large number of ECG recordings to reduce the waiting time of patients as well as reduce the workload on cardiologists and the cost of ECG signal processing.

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